# ORTHOGONAL TRACES ON SEMI-PRIME GAMMA RINGS 

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Abstract. We deal with some conditions in order that traces would be orthogonal on semiprime $\Gamma$-rings.

## 1. Introduction

In [8], J. Vukman proved some results related with symmetric bi-derivations on prime and semiprime rings, and then M. A. Öztürk et al. [5] applied the Vukman's idea to prime and semi-prime $\Gamma$-rings. In this paper, we consider (orthogonal) traces of symmetric biderivations on semi-prime $\Gamma$-rings, and we provide some conditions in order that traces would be orthogonal on semi-prime $\Gamma$-rings.

## 2. Preliminaries

Let $M$ and $\Gamma$ be two abelian groups. If for all $x, y, z \in M$ and all $\alpha, \beta \in \Gamma$ the conditions
(i) $x a y \in M$,
(ii) $(x+y) \alpha z=x \alpha z+y \alpha z, x(\alpha+\beta) z=x \alpha z+x \beta z, x \alpha(y+z)=x \alpha y+x \alpha z$,
(iii) $(x \alpha y) \beta z=x \alpha(y \beta z)$
are satisfied, then we call $M$ a $\Gamma$-ring. By a right (resp. left) ideal of a $\Gamma$-ring $M$ we mean an additive subgroup $U$ of $M$ such that $U \Gamma M \subseteq U$ (resp. $M \Gamma U \subseteq U$ ). If $U$ is both a right and a left ideal, then we say that $U$ is an ideal of $M$. For each $a$ of a $\Gamma$-ring $M$ the smallest right ideal containing $a$ is called the principal right ideal generated by $a$ and is denoted by $\langle a\rangle_{r}$. Similarly we define $\langle a\rangle_{l}$ (resp. $\langle a\rangle$ ), the principal left (resp. two sided) ideal generated by $a$. An ideal $P$ of a $\Gamma$-ring $M$ is said to be prime if for any ideals $A$ and $B$ of $M, A \Gamma B \subseteq P$ implies $A \subseteq P$ or $B \subseteq P$. An ideal $Q$ of a $\Gamma$-ring $M$ is said to be semi-prime if for any ideal $U$ of $M, U \Gamma U \subseteq Q$ implies $U \subseteq Q$. A $\Gamma$-ring $M$ is said to be prime (resp. semi-prime) if the zero ideal is prime (resp. semi-prime).

Theorem 2.1 ([3, Theorem 4]). If $M$ is a $\Gamma$-ring, the following conditions are equivalent:
(i) $M$ is a prime $\Gamma$-ring.
(ii) If $a, b \in M$ and $a \Gamma M \Gamma b=\langle 0\rangle$, then $a=0$ or $b=0$.
(iii) If $\langle a\rangle$ and $\langle b\rangle$ are principal ideals in $M$ such that $\langle a\rangle \Gamma\langle b\rangle=\langle 0\rangle$, then $a=0$ or $b=0$.
(iv) If $A$ and $B$ are right ideals in $M$ such that $A \Gamma B=\langle 0\rangle$, then $A=\langle 0\rangle$ or $B=\langle 0\rangle$.
(v) If $A$ and $B$ are left ideals in $M$ such that $A \Gamma B=\langle 0\rangle$, then $A=\langle 0\rangle$ or $B=\langle 0\rangle$.

Let $M$ be a $\Gamma$-ring. If there exists a least positive integer $n$ such that $n x=0$ for all $x \in M$, then $M$ is said to have characteristic $n$, denoted by char $M$. A $\Gamma$-ring $M$ is said to

[^0]be $n$-torsion free if $n x=0$ implies $x=0$ for any $x \in M$ and a positive integer $n$. If $M$ is a prime $\Gamma$-ring with char $M \neq n$, that is, there exists $0 \neq b \in M$ such that $n b \neq 0$, then $M$ is $n$-torsion free. Because if $n a=0$, then by $0=n a \Gamma M \Gamma n b$, we have $a=0$ which means that $M$ is $n$-torsion free.

Lemma 2.2 ([3, Corollary 1]). A $\Gamma$-ring $M$ is semi-prime if and only if $a \Gamma M \Gamma a=0$ implies $a=0$.

A mapping $D(\cdot, \cdot): M \times M \rightarrow M$ is said to be symmetric bi-additive if it is additive in both arguments and $D(x, y)=D(y, x)$ for all $x, y \in M$. By the trace of $D(\cdot, \cdot)$ we mean a $\operatorname{map} d: M \rightarrow M$ defined by $d(x)=D(x, x)$ for all $x \in M$. A symmetric bi-additive map is called a symmetric bi-derivation if $D(x \beta z, y)=D(x, y) \beta z+x \beta D(z, y)$ for all $x, y, z \in M$ and $\beta \in \Gamma$. Since a map $D(\cdot, \cdot)$ is symmetric bi-additive, the trace of $D(\cdot, \cdot)$ satisfies the relation $d(x+y)=d(x)+d(y)+2 D(x, y)$ for all $x, y \in M$, and is an even function.

Definition 2.3 ([6, Definition 2.1]). Let $M$ be a semi-prime $\Gamma$-ring, and let $D_{1}(\cdot, \cdot)$ and $D_{2}(\cdot, \cdot)$ be symmetric bi-derivations of $M$. If the traces $d_{1}$ and $d_{2}$ of $D_{1}(\cdot, \cdot)$ and $D_{2}(\cdot, \cdot)$, respectively, satisfy $d_{1}(x) \Gamma M \Gamma d_{2}(y)=0=d_{2}(y) \Gamma M \Gamma d_{1}(x)$ for all $x, y \in M$, then $d_{1}$ and $d_{2}$ are called orthogonal traces.

Note that, the trace of a non-zero symmetric bi-derivation in a semi-prime $\Gamma$-ring isn't orthogonal with itself. Let $M$ be a $\Gamma$-ring. For a subset $S$ of $M, l(S)=\{a \in M \mid a \Gamma S=0\}$ is called the left annihilator of $S$. A right annihilator $r(S)$ can be defined similarly.

Lemma 2.4 ([5, Lemma 3]). Let $M$ be a 2-torsion free semi-prime $\Gamma$-ring, $U$ a non-zero ideal of $M$ and $a, b \in M$. Then the following are equivalent.
(i) $a \alpha x \beta b=0$ for all $x \in U$ and $\alpha, \beta \in \Gamma$,
(ii) $b \alpha x \beta a=0$ for all $x \in U$ and $\alpha, \beta \in \Gamma$,
(iii) $a \alpha x \beta b+b \alpha x \beta a=0$ for all $x \in U$ and $\alpha, \beta \in \Gamma$.

If one of the conditions is fulfilled and $l(U)=0$, then $a \alpha b=0=b \alpha a$ for all $\alpha \in \Gamma$. Moreover if $M$ is a prime $\Gamma$-ring, then $a=0$ or $b=0$.
Lemma 2.5 ([5, Lemma 4]). Let $M$ be a 2, 3-torsion free semi-prime $\Gamma$ - ring and $U$ a non-zero ideal of $M$. Let $D_{1}(\cdot, \cdot)$ and $D_{2}(\cdot, \cdot)$ be symmetric bi-derivations of $M$, and let $d_{1}$ and $d_{2}$ be the traces of $D_{1}(\cdot, \cdot)$ and $D_{2}(\cdot, \cdot)$ respectively. Then
(i) If $d_{1}(U) \Gamma U \Gamma d_{2}(U)=0$, then $d_{1}(M) \Gamma U \Gamma d_{2}(M)=0$,
(ii) If $l(U)=0$ and $d_{1}(M) \Gamma U \Gamma d_{2}(M)=0$, then $d_{1}(M) \Gamma M \Gamma d_{2}(M)=0$.

## 3. Main results

Theorem 3.1. Let $M$ be a 2, 3-torsion free semi-prime $\Gamma$-ring, $U$ a non-zero ideal of $M$ and $l(U)=0$. Let $D_{1}(\cdot, \cdot)$ and $D_{2}(\cdot, \cdot)$ be symmetric bi-derivations of $M$, and let $d_{1}$ and $d_{2}$ be the traces of $D_{1}(\cdot, \cdot)$ and $D_{2}(\cdot, \cdot)$ respectively. Then $d_{1}$ and $d_{2}$ are orthogonal if and only if $d_{1}(u) \Gamma d_{2}(v)+d_{2}(u) \Gamma d_{1}(v)=0$ for all $u, v \in U$.
Proof. If $d_{1}$ and $d_{2}$ are orthogonal, then $d_{1}(x) \Gamma M \Gamma d_{2}(y)=0=d_{2}(y) \Gamma M \Gamma d_{1}(x)$ for all $x, y \in M$. So we have $d_{1}(u) \Gamma d_{2}(v)=0=d_{2}(v) \Gamma d_{1}(u)$ by Lemma 2.4, and hence

$$
d_{1}(u) \Gamma d_{2}(v)+d_{2}(u) \Gamma d_{1}(v)=0
$$

for all $u, v \in U$. Conversely, assume that $d_{1}(u) \Gamma d_{2}(v)+d_{2}(u) \Gamma d_{1}(v)=0$ for all $u, v \in U$. Then

$$
\begin{equation*}
d_{1}(u) \gamma d_{2}(v)+d_{2}(u) \gamma d_{1}(v)=0 \tag{1}
\end{equation*}
$$

for all $u, v \in U$ and $\gamma \in \Gamma$. Replacing $v$ by $v+w$ in (1) where $w \in U$ and using the fact that $M$ is 2-torsion free, we get

$$
\begin{equation*}
d_{1}(u) \gamma D_{2}(v, w)+d_{2}(u) \gamma D_{1}(v, w)=0 \tag{2}
\end{equation*}
$$

for all $u, v, w \in U$ and $\gamma \in \Gamma$. Substituting $u+v$ for $u$ in (2) we have

$$
\begin{equation*}
D_{1}(u, v) \gamma D_{2}(v, w)+D_{2}(u, v) \gamma D_{1}(v, w)=0 \tag{3}
\end{equation*}
$$

for all $u, v, w \in U$ and $\gamma \in \Gamma$. Now replacing $w$ by $w \beta u$ in (3) where $\beta \in \Gamma$ and using (3), we obtain

$$
\begin{equation*}
D_{1}(u, v) \gamma w \beta D_{2}(v, u)+D_{2}(u, v) \gamma w \beta D_{1}(v, u)=0 \tag{4}
\end{equation*}
$$

for all $u, v, w \in U$ and $\gamma, \beta \in \Gamma$. Substituting $u$ for $v$ in (4), we get

$$
\begin{equation*}
d_{1}(u) \gamma w \beta d_{2}(u)+d_{2}(u) \gamma w \beta d_{1}(u)=0 \tag{5}
\end{equation*}
$$

for all $u, w \in U$ and $\gamma, \beta \in \Gamma$. It follows from (5) and Lemma 2.4 that $d_{1}(u) \Gamma U \Gamma d_{2}(u)=0$ for all $u \in U$. In a similar way, we get $d_{2}(u) \Gamma U \Gamma d_{1}(u)=0$ for all $u \in U$. This shows that $d_{1}$ is orthogonal with $d_{2}$ by Lemma 2.5 .

Theorem 3.2. Let $M$ be a 2,3-torsion free semi-prime $\Gamma$-ring, $U$ a non-zero ideal of $M$ and $l(U)=0$. Let $D_{1}(\cdot, \cdot)$ and $D_{2}(\cdot, \cdot)$ be symmetric bi-derivations of $M$ such that $d_{2}(U) \subset$ $U$ and $d_{1}$ and $d_{2}$ the traces of $D_{1}(\cdot, \cdot)$ and $D_{1}(\cdot, \cdot)$ respectively. Then the following are equivalent:
(i) $d_{1}$ and $d_{2}$ are orthogonal,
(ii) $d_{1} d_{2}=0$,
(iii) There exists $a, b \in M$ and $\gamma, \beta \in \Gamma$ such that $\left(d_{1} d_{2}\right)(u)=a \beta u+u \gamma b$ for all $u \in U$,
(iv) $d_{1} d_{2}=f$, where $f$ is the trace of a symmetric bi-additive mapping $F(\cdot, \cdot)$ of $M$.

Proof. (i) $\Rightarrow$ (ii), (i) $\Rightarrow$ (iii) and (i) $\Rightarrow$ (iv) are given in [6, Theorem 2.7].
(ii) $\Rightarrow$ (i): Assume that $d_{1} d_{2}=0$. Then

$$
\begin{equation*}
\left(d_{1} d_{2}\right)(u)=0 \text { for all } u \in U . \tag{6}
\end{equation*}
$$

Since $M$ is 2 -torsion free, by linearizing (6) we obtain

$$
\begin{align*}
& D_{1}\left(d_{2}(u), d_{2}(v)\right)+2 D_{1}\left(D_{2}(u, v), d_{2}(v)\right) \\
& \quad+2 D_{1}\left(D_{2}(u, v), d_{2}(u)\right)+4 D_{1}\left(D_{2}(u, v), D_{2}(u, v)\right)=0 \tag{7}
\end{align*}
$$

for all $u, v \in U$. Substituting $-u$ for $u$ in (7), we have

$$
\begin{align*}
& D_{1}\left(d_{2}(u), d_{2}(v)\right)-2 D_{1}\left(D_{2}(u, v), d_{2}(v)\right)  \tag{8}\\
& \quad-2 D_{1}\left(D_{2}(u, v), d_{2}(u)\right)+4 D_{1}\left(D_{2}(u, v), D_{2}(u, v)\right)=0
\end{align*}
$$

for all $u, v \in U$. Adding (7) and (8) and using the fact that $M$ is 2-torsion free, we obtain

$$
\begin{equation*}
D_{1}\left(d_{2}(u), d_{2}(v)\right)+2 D_{1}\left(D_{2}(u, v), D_{2}(u, v)\right)=0 \tag{9}
\end{equation*}
$$

for all $u, v \in U$. Substituting $u+w$ for $u$ in (9) where $w \in U$ and using the fact that $M$ is 2-torsion free, we have

$$
\begin{equation*}
D_{1}\left(D_{2}(u, w), d_{2}(v)\right)+2 D_{1}\left(D_{2}(u, v), D_{2}(w, v)\right)=0 \tag{10}
\end{equation*}
$$

for all $u, v, w \in U$. Replacing $u$ by $u \gamma k$ in (10) where $k \in U$ and $\gamma \in \Gamma$ and using (10) again, we have

$$
\begin{align*}
D_{2}(u, w) & \gamma D_{1}\left(k, d_{2}(v)\right)+D_{1}\left(u, d_{2}(v)\right) \gamma D_{2}(k, w) \\
& +2 D_{1}\left(u, D_{2}(w, v) \gamma D_{2}(k, v)\right)  \tag{11}\\
& +2 D_{2}(u, v) \gamma D_{1}\left(k, D_{2}(w, v)\right)=0
\end{align*}
$$

for all $u, v, w, k \in U$ and $\gamma \in \Gamma$. Since $M$ is 3-torsion free, by substituting $v$ for $w$ in (11) we get

$$
\begin{equation*}
D_{2}(u, v) \gamma D_{1}\left(k, d_{2}(v)\right)+D_{1}\left(u, d_{2}(v)\right) \gamma D_{2}(k, v)=0 \tag{12}
\end{equation*}
$$

for all $u, v, k \in U$ and $\gamma \in \Gamma$. Using $k \beta u$ for $k$ in (12) where $\beta \in \Gamma$, we get

$$
\begin{equation*}
D_{2}(u, v) \gamma k \beta D_{1}\left(u, d_{2}(v)\right)+D_{1}\left(u, d_{2}(v)\right) \gamma k \beta D_{2}(u, v)=0 \tag{13}
\end{equation*}
$$

for all $u, v, k \in U$ and $\gamma, \beta \in \Gamma$. It follows from Lemma 2.4 that

$$
\begin{equation*}
D_{2}(u, v) \gamma k \beta D_{1}\left(u, d_{2}(v)\right)=0 \tag{14}
\end{equation*}
$$

for all $u, v, k \in U$ and $\gamma, \beta \in \Gamma$. Writing $v+w$ for $v$ in (14) and by using (14), we get

$$
\begin{align*}
D_{2}(u, v) & \gamma k \beta D_{1}\left(u, d_{2}(w)\right)+D_{2}(u, w) \gamma k \beta D_{1}\left(u, d_{2}(v)\right) \\
& +2 D_{2}(u, v) \gamma k \beta D_{1}\left(u, D_{2}(v, w)\right)  \tag{15}\\
& +2 D_{2}(u, w) \gamma k \beta D_{1}\left(u, D_{2}(v, w)\right)=0
\end{align*}
$$

for all $u, v, k, w \in U$ and $\gamma, \beta \in \Gamma$. Replacing $w$ by $-w$ in (15), we have

$$
\begin{align*}
-D_{2}(u, v) & \gamma k \beta D_{1}\left(u, d_{2}(w)\right)-D_{2}(u, w) \gamma k \beta D_{1}\left(u, d_{2}(v)\right) \\
& -2 D_{2}(u, v) \gamma k \beta D_{1}\left(u, D_{2}(v, w)\right)  \tag{16}\\
& +2 D_{2}(u, w) \gamma k \beta D_{1}\left(u, D_{2}(v, w)\right)=0
\end{align*}
$$

for all $u, v, k, w \in U$ and $\gamma, \beta \in \Gamma$. Adding up (15) and (16) and using the fact that $M$ is 2-torsion free, we obtain

$$
\begin{equation*}
D_{2}(u, v) \gamma k \beta D_{1}\left(u, d_{2}(w)\right)+2 D_{2}(u, w) \gamma k \beta D_{1}\left(u, D_{2}(v, w)\right)=0 \tag{17}
\end{equation*}
$$

for all $u, v, k, w \in U$ and $\gamma, \beta \in \Gamma$. Replacing $k$ by $k \beta D_{1}\left(d_{2}(w), u\right) \beta^{\prime} m \gamma^{\prime} D_{2}(u, v) \gamma k$ in (17) where $m \in M$ and $\gamma^{\prime}, \beta^{\prime} \in \Gamma$ and using (15) and the fact that $M$ is a semi-prime $\Gamma$-ring, we get

$$
\begin{equation*}
D_{2}(u, v) \gamma k \beta D_{1}\left(d_{2}(w), u\right)=0 \tag{18}
\end{equation*}
$$

for all $u, v, k, w \in U$ and $\gamma, \beta \in \Gamma$. Substituting $w+p$ for $w$ in (18) where $p \in U$ and using the fact that $M$ is 2 -torsion free, we have

$$
\begin{equation*}
D_{2}(u, v) \gamma k \beta D_{1}\left(D_{2}(w, p), u\right)=0 \tag{19}
\end{equation*}
$$

for all $u, v, k, w, p \in U$ and $\gamma, \beta \in \Gamma$. Writing $k \gamma^{\prime} t$ for $k$ in (19) where $t \in U$ and $\gamma^{\prime} \in \Gamma$, we get

$$
\begin{equation*}
D_{2}(u, v) \gamma k \gamma^{\prime} t \beta D_{1}\left(D_{2}(w, p), u\right)=0 \tag{20}
\end{equation*}
$$

for all $u, v, k, w, p, t \in U$ and $\gamma, \beta, \gamma^{\prime} \in \Gamma$. In the similar manner, writing $t \gamma^{\prime} w$ for $w$ in (20) and using (20), we have

$$
\begin{equation*}
D_{2}(u, v) \gamma k \beta D_{2}(t, p) \gamma^{\prime} D_{1}(w, u)+D_{2}(u, v) \gamma k \beta D_{1}(t, u) \gamma^{\prime} D_{2}(w, p)=0 \tag{21}
\end{equation*}
$$

for all $u, v, k, w, p, t \in U$ and $\gamma, \beta, \gamma^{\prime} \in \Gamma$. Writing $d_{2}(t)$ for $t$ in (21), it follows from (18) that

$$
\begin{equation*}
D_{2}(u, v) \gamma k \beta D_{2}\left(d_{2}(t), p\right) \gamma^{\prime} D_{1}(w, u)=0 \tag{22}
\end{equation*}
$$

for all $u, v, k, w, p, t \in U$ and $\gamma, \beta, \gamma^{\prime} \in \Gamma$. Writing $t+q$ for $t$ in (22) where $q \in U$ and using the fact that $M$ is 2 -torsion free, we get

$$
\begin{equation*}
D_{2}(u, v) \gamma k \beta D_{2}\left(D_{2}(t, q), p\right) \gamma^{\prime} D_{1}(w, u)=0 \tag{23}
\end{equation*}
$$

for all $u, v, k, w, p, t, q \in U$ and $\gamma, \beta, \gamma^{\prime} \in \Gamma$. It follows by sustituting $k \beta^{\prime} r$ for $k$ in (23), where $r \in U$ and $\beta^{\prime} \in \Gamma$, that

$$
\begin{equation*}
D_{2}(u, v) \gamma k \beta^{\prime} r \beta D_{2}\left(D_{2}(t, q), p\right) \gamma^{\prime} D_{1}(w, u)=0 \tag{24}
\end{equation*}
$$

for all $u, v, k, w, p, t, q, r \in U$ and $\gamma, \beta, \gamma^{\prime}, \beta^{\prime} \in \Gamma$. Again, writing $r \beta^{\prime} w$ for $w$ in (23), we have

$$
\begin{equation*}
D_{2}(u, v) \gamma k \beta^{\prime} r \beta D_{2}\left(D_{2}(t, q), p\right) \gamma^{\prime} r \beta^{\prime} D_{1}(w, u)=0 \tag{25}
\end{equation*}
$$

for all $u, v, k, w, p, t, q, r \in U$ and $\gamma, \beta, \gamma^{\prime}, \beta^{\prime} \in \Gamma$. Substituting $r \beta^{\prime} t$ for $t$ in (23) and using (24)and (25), we have

$$
\begin{align*}
D_{2}(u, v) & \gamma k \beta D_{2}(r, p) \beta^{\prime} D_{2}(t, q) \gamma^{\prime} D_{1}(w, u) \\
& +D_{2}(u, v) \gamma k \beta D_{2}(r, q) \beta^{\prime} D_{2}(t, p) \gamma^{\prime} D_{1}(w, u)=0 \tag{26}
\end{align*}
$$

for all $u, v, k, w, p, t, q, r \in U$ and $\gamma, \beta, \gamma^{\prime}, \beta^{\prime} \in \Gamma$. Since $M$ is 2-torsion free, it follows by replacing $q$ by $p$ in (26) that

$$
\begin{equation*}
D_{2}(u, v) \gamma k \beta D_{2}(r, p) \beta^{\prime} D_{2}(t, p) \gamma^{\prime} D_{1}(w, u)=0 \tag{27}
\end{equation*}
$$

for all $u, v, k, w, p, t \in U$ and $\gamma, \beta, \gamma^{\prime}, \beta^{\prime} \in \Gamma$. Replacing $k$ by $D_{2}(t, p) \gamma^{\prime} D_{1}(w, u) \alpha k \alpha^{\prime} m$ in (27) where $m \in M$ and $\alpha, \alpha^{\prime} \in \Gamma$, we have

$$
D_{2}(u, v) \gamma D_{2}(t, p) \gamma^{\prime} D_{1}(w, u) \alpha k \alpha^{\prime} m \beta D_{2}(r, p) \beta^{\prime} D_{2}(t, p) \gamma^{\prime} D_{1}(w, u)=0
$$

Taking $\beta^{\prime}$ for $\gamma$ and $u, v$ for $r, p$ respectively in the previous equation and using $l(U)=0$, we have

$$
\begin{equation*}
D_{2}(u, v) \gamma D_{2}(t, v) \beta D_{1}(w, u)=0 \tag{28}
\end{equation*}
$$

for all $u, v, w, t \in U$ and $\gamma, \beta \in \Gamma$. Replacing $w$ by $k \gamma^{\prime} w$ in (28), we get

$$
\begin{equation*}
D_{2}(u, v) \gamma D_{2}(t, v) \beta k \gamma^{\prime} D_{1}(w, u)=0 \tag{29}
\end{equation*}
$$

for all $u, v, k, w, t \in U$ and $\gamma, \beta, \gamma^{\prime} \in \Gamma$. Again, replacing $t$ by $t \gamma^{\prime} k$ in (28) and using (29), we get

$$
\begin{equation*}
D_{2}(u, v) \gamma t \gamma^{\prime} D_{2}(k, v) \beta D_{1}(w, u)=0 \tag{30}
\end{equation*}
$$

for all $u, v, k, w, t \in U$ and $\gamma, \beta, \gamma^{\prime} \in \Gamma$. Replacing $t$ by $D_{1}(w, u) \alpha t \beta^{\prime} m$ in (30) where $m \in M$, we have

$$
\begin{equation*}
D_{2}(u, v) \gamma D_{1}(w, u) \alpha t \beta^{\prime} m \gamma^{\prime} D_{2}(k, v) \beta D_{1}(w, u)=0 \tag{31}
\end{equation*}
$$

for all $u, v, w, k, t \in U$ and $\gamma, \beta^{\prime}, \gamma^{\prime} \in \Gamma$ and $m \in M$. Writing $\beta$ for $\gamma$ and writing $u$ for $k$ in (31), it follows from $l(U)=0$ that

$$
\begin{equation*}
D_{2}(u, v) \beta D_{1}(w, u)=0 \tag{32}
\end{equation*}
$$

for all $u, v, w \in U$ and $\beta \in \Gamma$. Now, writing $w \gamma v$ for $w$ in (32), we get

$$
D_{2}(u, v) \beta w \gamma D_{1}(u, v)=0
$$

for all $u, v, w \in U$ and $\gamma, \beta \in \Gamma$, and so by taking $u$ for $v$ in the previous equation, we get $d_{2}(x) \Gamma M \Gamma d_{2}(y)=0$ for all $x, y \in M$ by Lemma 2.5. Similarly, we get $d_{1}(y) \Gamma M \Gamma d_{2}(x)=0$ for all $x, y \in M$.
(iii) $\Rightarrow$ (i): Assume that there exists $a, b \in M$ and $\gamma, \beta \in \Gamma$ such that $\left(d_{1} d_{2}\right)(u)=$ $a \beta u+u \gamma b$ for all $u \in U$. Then by linearizing and using the fact that $M$ is a 2-torsion free, we get

$$
\begin{align*}
& D_{1}\left(d_{2}(u), d_{2}(v)\right)+2 D_{1}\left(D_{2}(u, v), d_{2}(u)\right) \\
& \quad+2 D_{1}\left(D_{2}(u, v), d_{2}(v)\right)+2 D_{1}\left(D_{2}(u, v), D_{2}(u, v)\right)=0 \tag{33}
\end{align*}
$$

for all $u, v \in U$. Applying all steps which start from (7), we get the result.
(iv) $\Rightarrow(\mathrm{i})$ : Let $\left(d_{1} d_{2}\right)(u)=f(u)$, where $f$ is the trace of a symmetric bi-additive mapping $F(\cdot, \cdot)$ of $M$. By linearizing this expression and by using the fact that $M$ is 2-torsion free, we get

$$
\begin{align*}
& D_{1}\left(d_{2}(u), d_{2}(v)\right)+2 D_{1}\left(D_{2}(u, v), d_{2}(u)\right) \\
& \quad+2 D_{1}\left(D_{2}(u, v), d_{2}(v)\right)+2 D_{1}\left(D_{2}(u, v), D_{2}(u, v)\right)=F(u, v) \tag{34}
\end{align*}
$$

for all $u, v \in U$. Writing $-u$ for $u$ in (34), we get

$$
\begin{align*}
& D_{1}\left(d_{2}(u), d_{2}(v)\right)-2 D_{1}\left(D_{2}(u, v), d_{2}(u)\right)  \tag{35}\\
& \quad-2 D_{1}\left(D_{2}(u, v), d_{2}(v)\right)+2 D_{1}\left(D_{2}(u, v), D_{2}(u, v)\right)=-F(u, v)
\end{align*}
$$

for all $u, v \in U$. Adding (34) and (35) and using the fact that $M$ is 2-torsion free, we get

$$
\begin{equation*}
D_{1}\left(d_{2}(u), d_{2}(v)\right)+2 D_{1}\left(D_{2}(u, v), D_{2}(u, v)\right)=0 \tag{36}
\end{equation*}
$$

for all $u, v \in U$. Thus, applying all steps which start from (8) we get the result. Hence the proof of the theorm is completed.

Corollary 3.3. Let $M$ be a 2,3 -torsion free prime $\Gamma$-ring and $U$ a non-zero ideal of $M$. Let $D_{1}(\cdot, \cdot), D_{2}(\cdot, \cdot)$ be symmetric bi-derivations of $M$ such that $d_{2}(u) \subset U$ and $d_{1}$ and $d_{2}$ the traces of $D_{1}(\cdot, \cdot)$ and $D_{2}(\cdot, \cdot)$, respectively. If one of the equivalent conditions in Theorem 3.2 is valid, then $D_{1}=0$ or $D_{2}=0$.

Corollary 3.4. Let $M$ be a 2, 3 -torsion free semi-prime $\Gamma$-ring and $U$ a non-zero ideal of $M$. Let $D(\cdot, \cdot)$ be a symmetric bi-derivation of $M$ such that $d(u) \subset D(\cdot, \cdot)$ and $d$ the traces of $D(\cdot, \cdot)$. If one of the equivalent conditions in Theorem 3.2 is valid, then $D=0$.

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